

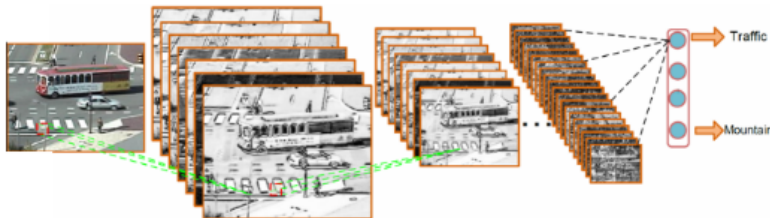
Neural Networks and Deep Learning: Representation Learning with ConvNets

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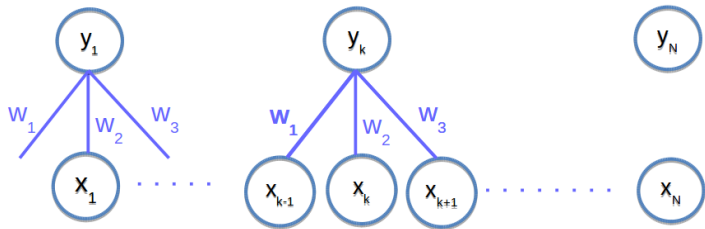
Deep ConvNets

- ▶ Deep models: hierarchy of sequential layers
 - convolution + non linearity
- ▶ Layers: fully connected, convolution layer, pooling
- ▶ Supervised training for classification
⇒ **Representation Learning**



Error Back-Propagation ConvNets

- **Convolution:** example for 1d scalar conv with mask $\mathbf{w} = [w_1 \ w_2 \ w_3]^T$



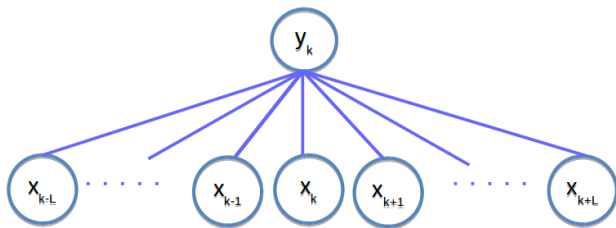
- **Shared weights:** simple chain rule application

⇒ Sum gradients for every region y_k !

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \sum_{k=1}^N \frac{\partial \mathcal{L}}{\partial y_k} \frac{\partial y_k}{\partial \mathbf{w}} \quad - \quad \frac{\partial y_k}{\partial \mathbf{w}} = [x_{k-1} \ x_k \ x_{k+1}]^T$$

Error Back-Propagation with ConvNets

- ▶ **Pooling:** example for pooling area of size $2L + 1$:
- ▶ $y_k = f(x_{k-L}, \dots, x_{k+L})$



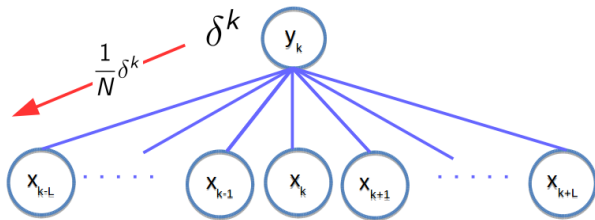
$$\frac{\partial \mathcal{L}}{\partial x_h} = \frac{\partial \mathcal{L}}{\partial y_k} \frac{\partial y_k}{\partial x_h} = \delta^k \frac{\partial y_k}{\partial x_h}$$

Error Back-Propagation for Average pooling

- ▶ Average pooling: $y_k = \frac{1}{N} \sum_{h=k-L}^{k+L} x_h$

$$\frac{\partial \mathcal{L}}{\partial x_h} = \delta^k \frac{\partial y_k}{\partial x_h} = \frac{1}{N} \delta^k$$

⇒ Gradient propagated through each input node ($\frac{1}{N}$)

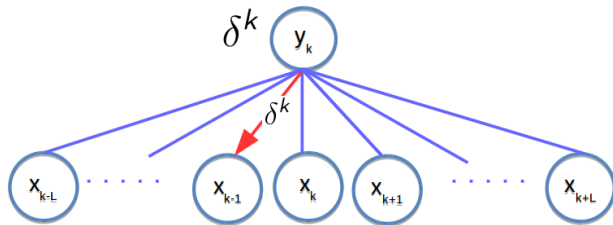


Error Back-Propagation for Max pooling

- Max pooling: $y_k = \max_{h'} x_h$

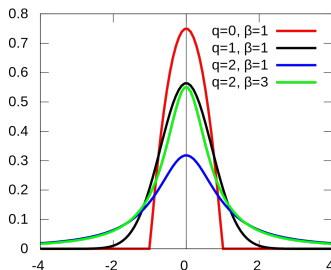
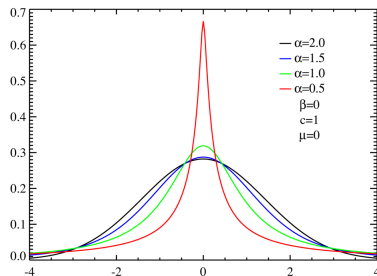
$$\frac{\partial \mathcal{L}}{\partial x_h} = \begin{cases} \delta^k & \text{if } x_h = \max_{h' \in \{k-L, \dots, k+L\}} x_{h'} \\ 0 & \text{otherwise} \end{cases}$$

⇒ Gradient propagated through arg max input node



ConvNets & Prior Distribution

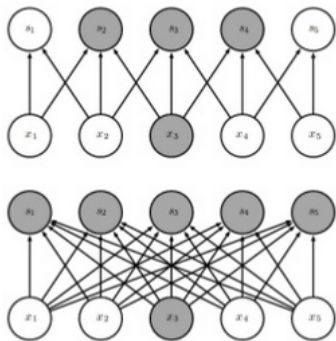
- ▶ **Prior:** imposing distribution on fully connected parameters
- ▶ Weak prior: high entropy (uncertainty), strong prior: low entropy
- ▶ **Infinitely strong prior:** zero probability on some parameters



ConvNet as Infinitely Strong Prior

- ▶ ConvNet \sim Infinitely Strong Prior on Fully Connected net weights
- ▶ Convolution: local interactions, shared weights \Rightarrow zero probability elsewhere

Sparse Interactions



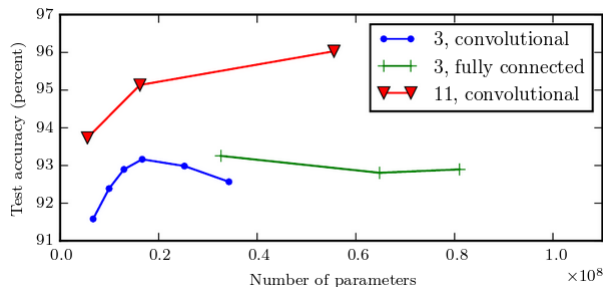
ConvNet for Learning Representation

- ▶ ConvNet ~ Infinitely Strong Prior on Fully Connected net weights
- ▶ N.B.: weights adjusted for classification with back-prop
- ▶ Convolution \Rightarrow support learning translation-equivariant features
- ▶ Pooling \Rightarrow support features invariant (stable) wrt local translations



ConvNet for Learning Representation

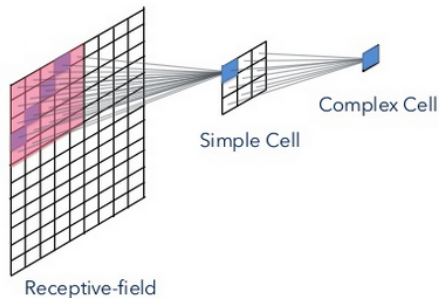
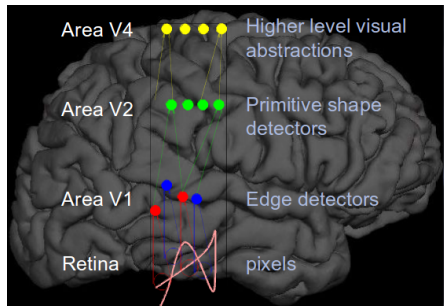
- ▶ ConvNet Infinitely Strong Prior: adapted to data with local interactions, e.g. image, speech, etc
- ▶ Very rich modeling capacities: local interactions \Rightarrow global with depth
- ▶ Significantly reduce # parameters \Rightarrow reducing over-fitting



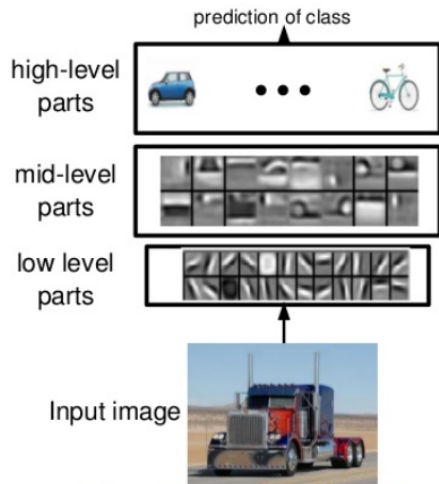
From [Goodfellow et al., 2016]

ConvNet for Learning Compositions

- ▶ **Conv/Pool hierarchies: feature composition**
 - ▶ Depth: gradual complexity, larger spatial extend
 - ▶ Intuitive processing for hierarchical information modeling
 - ▶ Biological foundations: simple cells, complex cells



ConvNet for Learning Compositions



Credit: M.A Ranzato

► Hierarchical Compositions

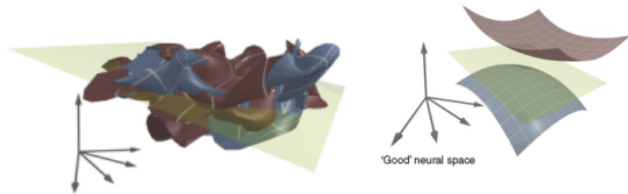
- Low-level: edges, color
- Mid-level: corner, parts
- Higher levels: objects, scene concepts

► Distributed Representations: sharing

- Lower-level: shared by many classes
- Higher-levels: more class specific

Representation Learning with Deep ConvNets: Conclusion

- ▶ Back-prop with ConvNets: **simple chain rule for Conv / Pool**
- ▶ Conv / Pool relevant *prior*: **learning good features for low-level signals**
- ▶ Conv / Pool hierarchies: **learning composition of parts**
- ▶ **Deep Learning & Manifold untangling?**
⇒ following!



References I



Goodfellow, I., Bengio, Y., and Courville, A. (2016).

Deep Learning.

MIT Press.

<http://www.deeplearningbook.org>.