

Towards the use of CNNs to constrain the phytoplankton community response to environmental changes

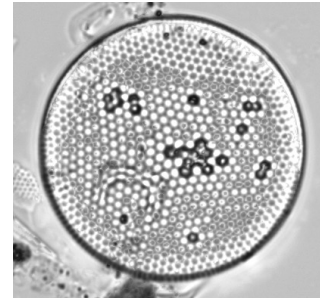
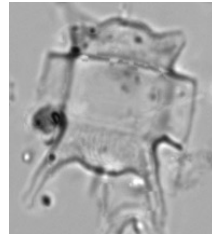
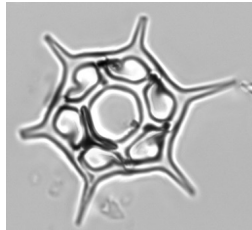
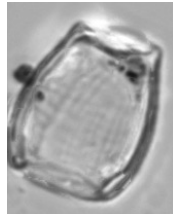
– An example from the Mediterranean Sea –

Camille Godbillot

CEREGE: Luc Beaufort, Yves Gally, Ross Marchant, Baptiste Pesenti, Thibault de Garidel-Thoron

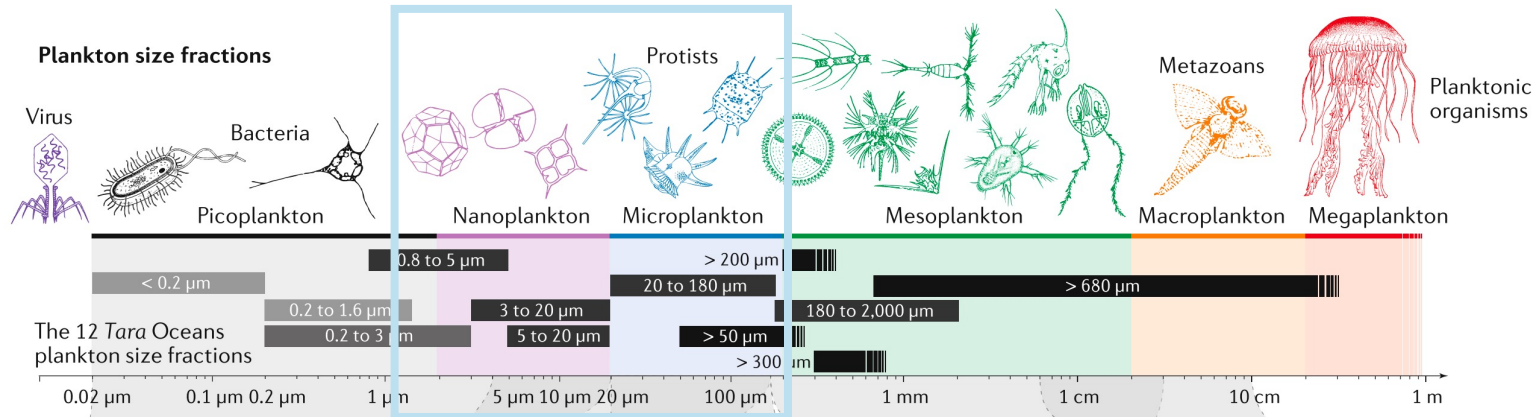
MIO: Karine Leblanc, Julien di Pane, Thang D.Q. Le, Cristele Chevalier

CEFREM: Xavier Durrieu de Madron



RESEARCH INTERESTS

Geochemical and morphological response of the phytoplankton community to environmental changes



Changes in assemblage + morphology

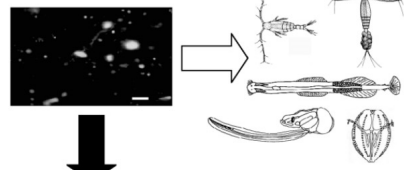
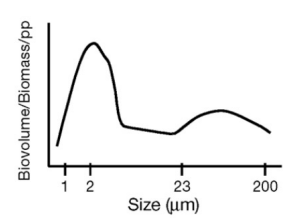
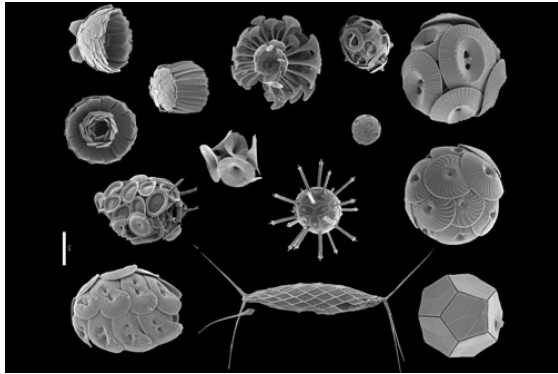
Species migrations
Morphological changes



RESEARCH INTERESTS

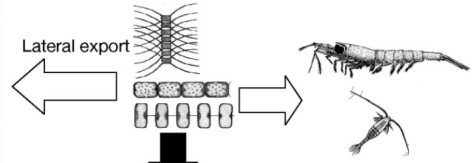
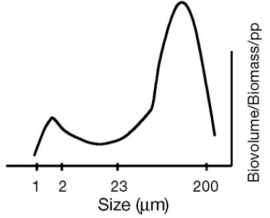
Geochemical and morphological response of the phytoplankton community to environmental changes

Coccolithophore-dominated community



Low PP export

Diatom-dominated community

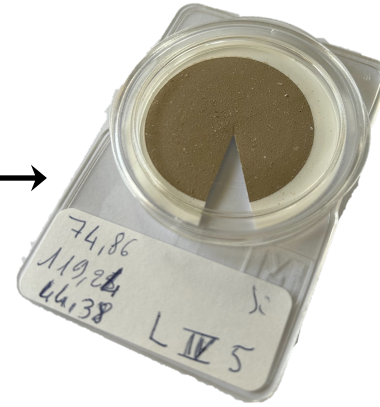
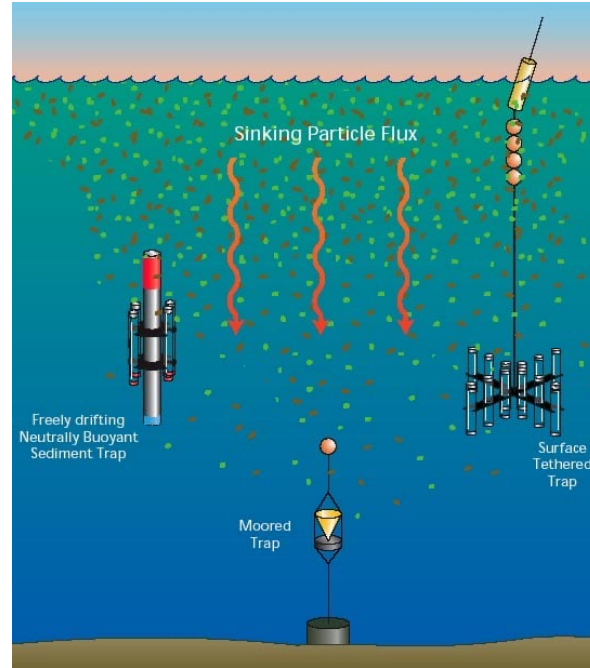
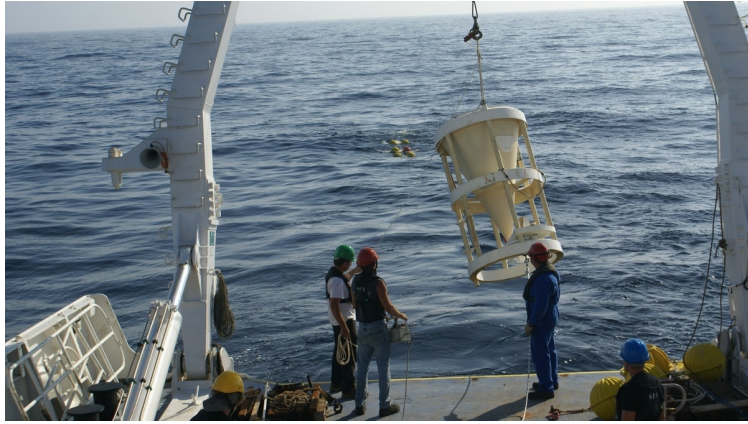


High PP export



Iriarte & González, 2004

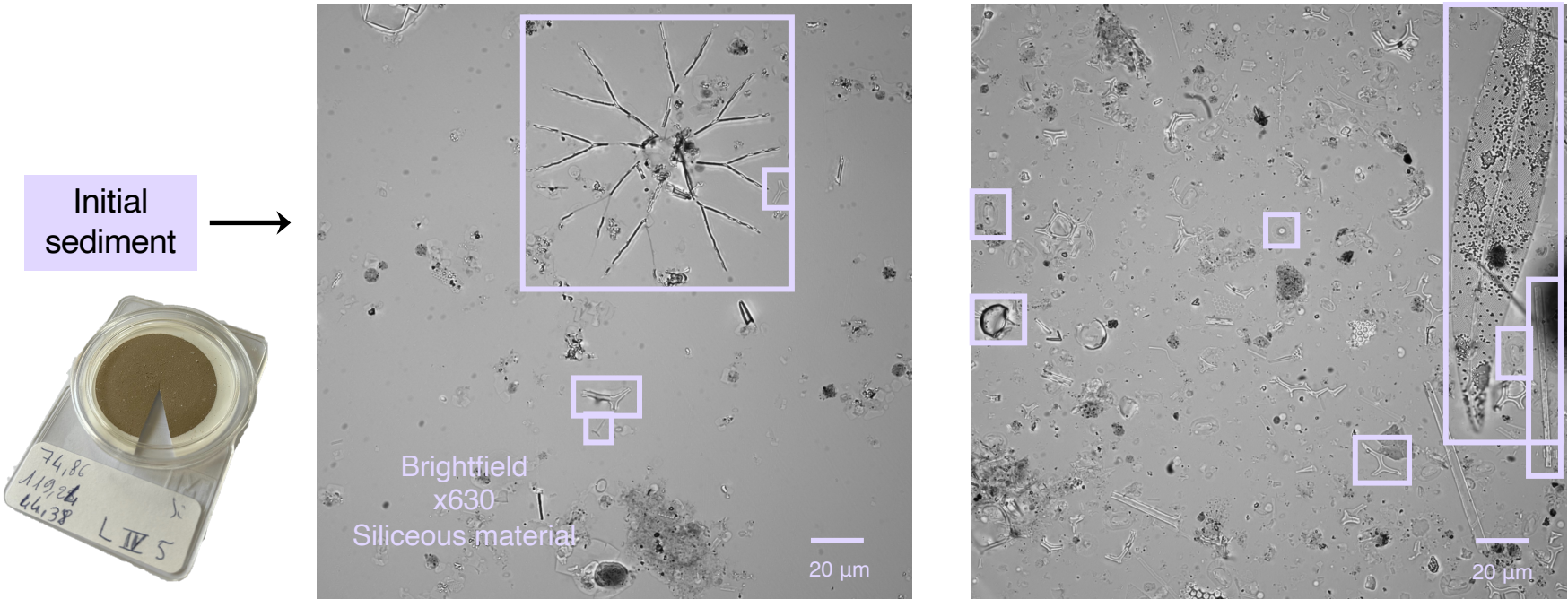
RESEARCH INTERESTS – STUDY OF SEDIMENT TRAPS



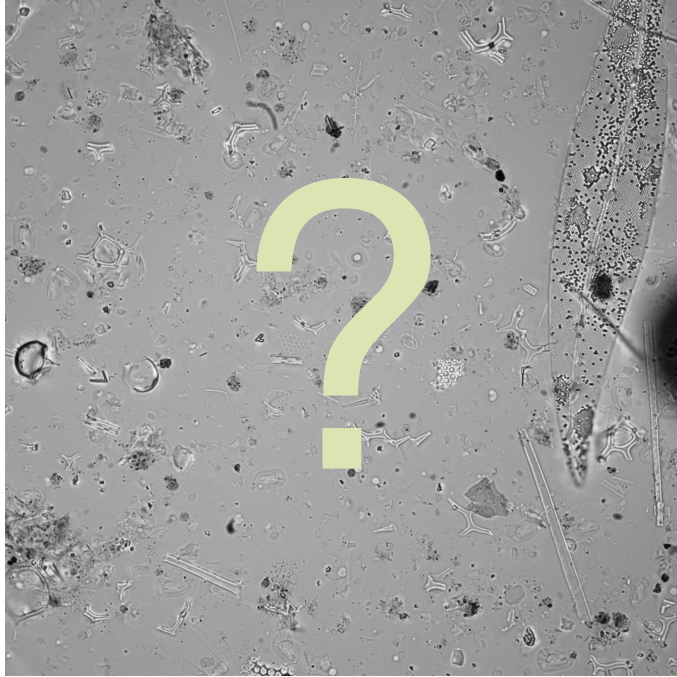
Sediment traps yield insight into the:

- **Biological production at the surface**
- **Carbon export to the sea floor**
- **Seasonal changes** in particle deposition

CONTEXT



Obtain **count** data + object **morphology** *i.e.*
length, [mass] (using birefringence)



Can we make this data acquisition automatic?

- Overlapping particles
- Differences in size and shapes
- Look similar to the background

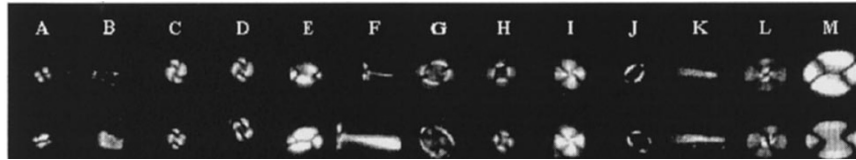
**New object detection workflows
can now be tested**

Overview of the methods used at CEREGE

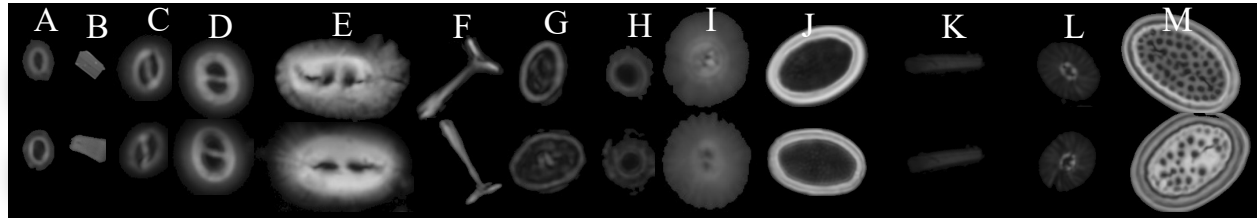
CONTEXT – OVERVIEW OF THE METHODS USED AT CEREGE

Image acquisition methods have improved, the classification methods have as well.

1996



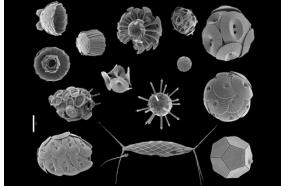
2020



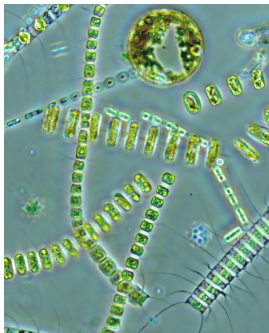
Year	Lens resolution	Camera (res. Spat.)	Pixel	Camera (niv. gris)	Polarisation	Focus	Slide preparation method	Patern recognition
1996	50X	0.5 Mpixel	0.3 μm	8 bits	Linear	Auto	Smear slides	CNN
2004	50X	0.5 Mpixel	0.3 μm	8 bits	Linear	Auto	Smear slides	Dyn CNN + hierarchy
2012	100X	4 Mpixel	0.062 μm	14 bits	Linear	Auto	Smear slides	Dyn CNN + hierarchy
2014	100X	4 Mpixel	0.062 μm	14 bits	Rotative / circular	Auto	Random settling	Dyn CNN + Random Forest
2020	100X	4 Mpixel	0.059 μm	16 bits	Bidirectional Circular	Multi-focus	Random settling 8 mini-lamelles	ResNet

CONTEXT – OVERVIEW OF THE METHODS USED AT CEREGE

Plateforme de micropaléontologie automatisée labellisée PRT (AMU, CNRS, INSERM)
depuis 2021



Groupe étudié	depuis	Personnel contributeur AI	Materiel impliqué
Coccolithes fossiles	1995	LB, CB, BSM, 4 thèses	4 micro-auto
Coccolithophores : plancton	2005	LB, 1 thèse, 1 post-doc	<i>idem</i>
Coccolithophores cultures	2017	LB, 1 Post-Doc	1 microinversé auto
Foraminifères planctoniques	2015	TdGT, 1 thèse, 1 post-doc	MISO + 2 binos auto
Foraminifères benthiques	2016	TdGT, LL, 1 thèse	<i>idem</i>
Radiolaires	2019	1 post doc, LB	1 micro-auto
Pollens	2018	DB, 2 thèses	<i>idem</i>
Diatomées	2022	1 post-doc	<i>idem</i>



LB: Luc Beaufort (DR), CB: Clara Bolton (CR), BSM : Baptiste Sucheras-Marx (MdC)
TdGT: Thibault de Garidel-Thoron (CR), LL : Laetitia Licari (MdC)
DB: Doris Barboni (CR)

ITA: Yves Gally (IR) – Jusqu'en 2022

CONTEXT – OVERVIEW OF THE METHODS USED AT CEREGE

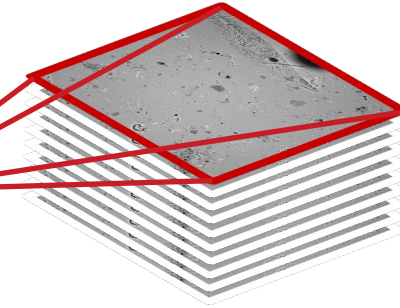
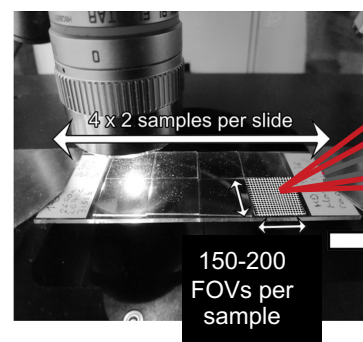
1) Image acquisition

2) Object detection

- Image annotation using CVAT (Computer Vision Annotation Tool)
- Model training
- Inference on images
- Cropping

3) Object classification

- Image library construction
- Model training
- Inference on new images



- Motorised optical microscope
- X630 – x1000 observations
- Polarized or brightfield lighting



Sediment samples

Image acquisition:

- > 200 images per sample
- Z-stacking
- ~ 1h per sample
- Possible to preset 16 samples

Images

CONTEXT – OVERVIEW OF THE METHODS USED AT CEREGE

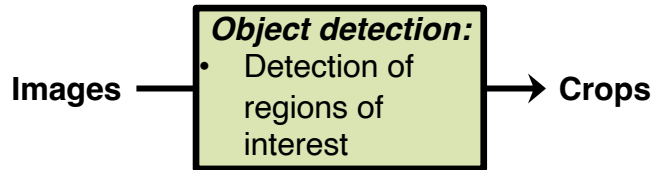
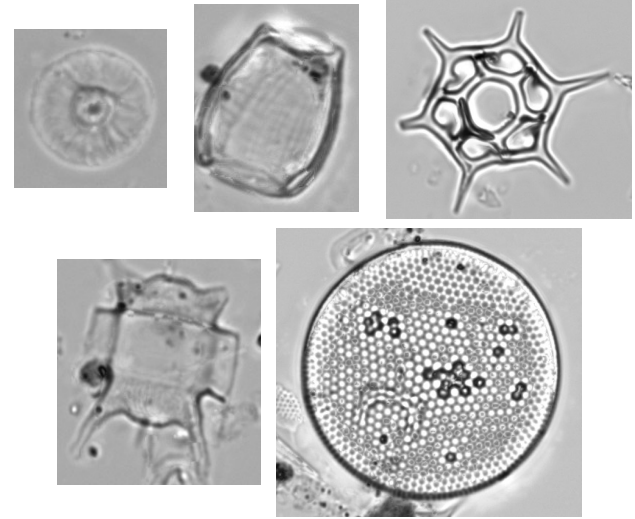
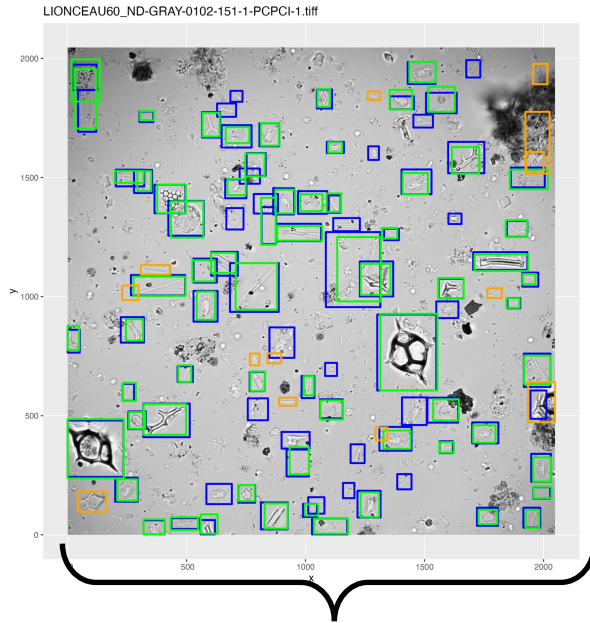
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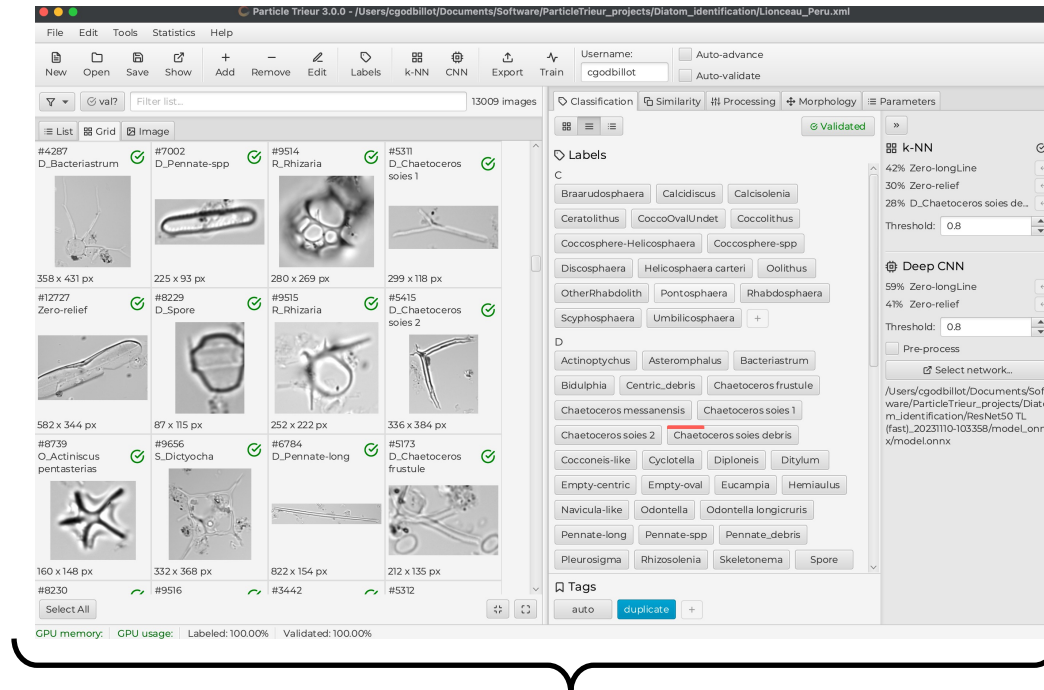
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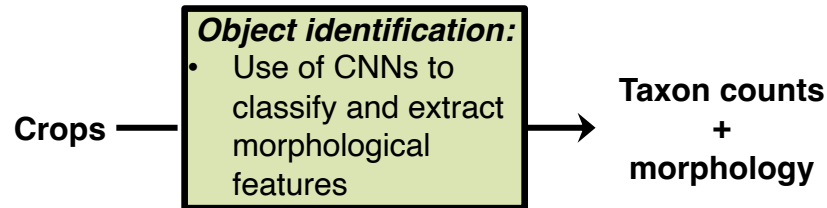
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ParticleTrieur



Object detection protocol

1) Image acquisition

2) Object detection

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Most recent workflow



Preprint available on ESS Open Archive:

A new method for the detection of siliceous microfossils on sediment microscope slides using convolutional neural networks

OBJECT DETECTION PROTOCOL

1) Image acquisition

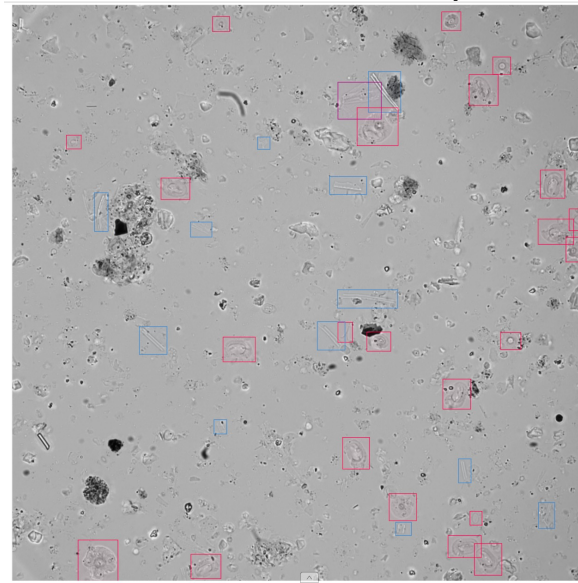
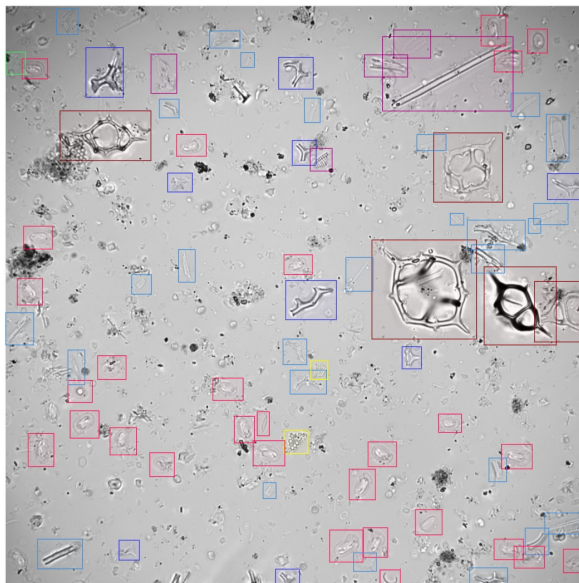
2) Object detection

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1) Image annotation using CVAT (Computer Vision Annotation Tool):



- 1 category “Microfossil” (merged all microfossils into a single category, no difference between silicoflagellates and diatoms for instance)
- 298 Images annotated (239 for training, 59 for testing): Mediterranean sediment + a sediment core from the coast of Peru
- 12 269 bounding boxes drawn

OBJECT DETECTION PROTOCOL

1) Image acquisition

2) Object detection

- Image annotation using CVAT (Computer Vision Annotation Tool)
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- Inference on images
- Cropping

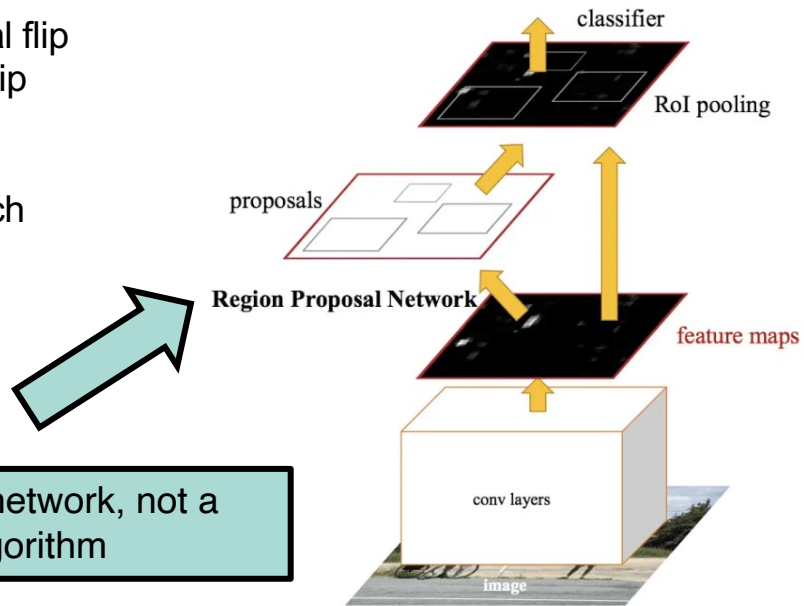
3) Object classification

- Image library construction
- Model training
- Inference on new images

1) Image annotation using CVAT (Computer Vision Annotation Tool)

2) Model training:

- Model:
 - ✓ Faster-RCNN with a ResNet50 backbone pre-trained on COCO
- Augmentations:
 - ✓ Random horizontal flip
 - ✓ Random vertical flip
 - ✓ Brightness
 - ✓ Contrast
- Implemented in PyTorch



Performed by a separate network, not a selective search algorithm

OBJECT DETECTION PROTOCOL

1) Image acquisition

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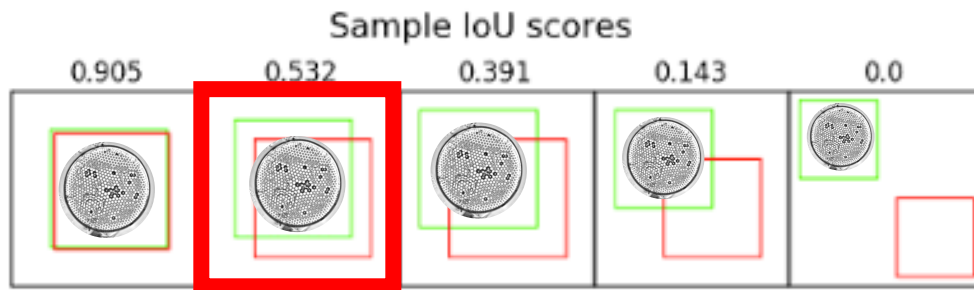
3) Object classification

- Image library construction
- Model training
- Inference on new images

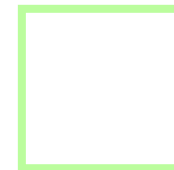
1) Image annotation using CVAT (Computer Vision Annotation Tool)

2) **Model training:**

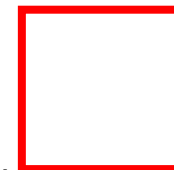
How to evaluate model performance ?



Ground-truth bounding box



Predicted bounding box



IoU = Area of Intersection of the two bboxes / Area of Union

→ In general, studies consider that the model has detected the ground-truth bbox when **the IoU > 0.5**

OBJECT DETECTION PROTOCOL

1) Image acquisition

2) Object detection

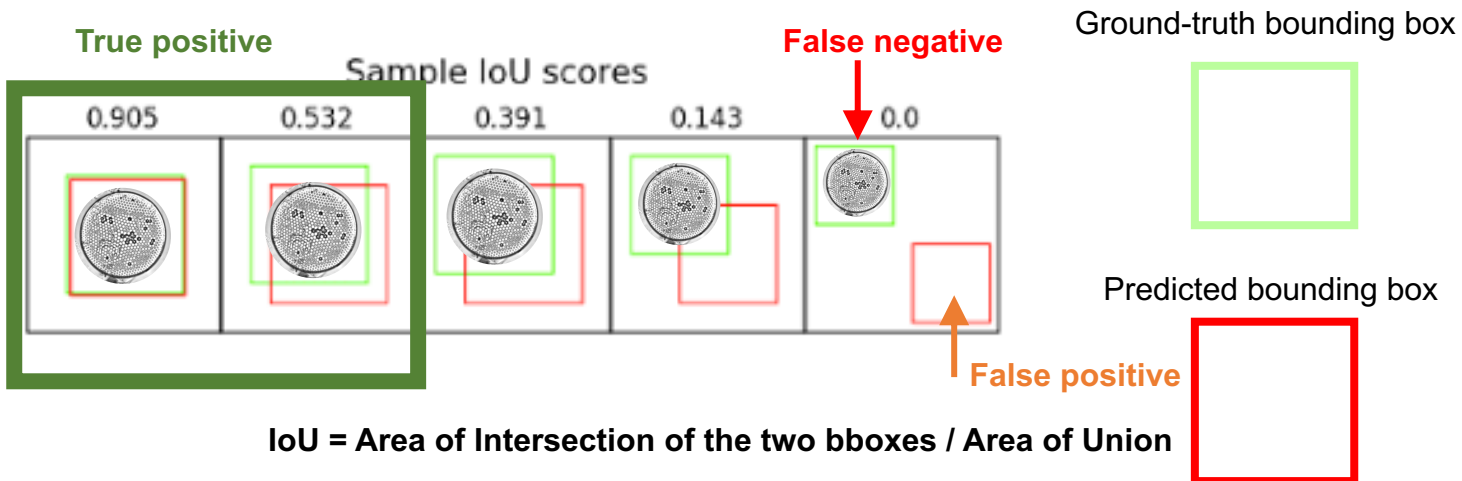
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3) Object classification

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- 1) Image annotation using CVAT (Computer Vision Annotation Tool)
- 2) **Model training:**

How to evaluate model performance ?



→ In general, studies consider that the model has detected the ground-truth bbox when **the IoU > 0.5**

→ Three cases can occur in **object detection**:

- **True Positive** : a **predicted** box has an IoU > 0.50 with a **ground-truth** box
- **False Negative** : a **ground-truth** box has **no corresponding predicted** box (IoU < 0.50)
- **False Positive** : a **predicted** box corresponds to **no ground-truth** box (IoU < 0.50)

OBJECT DETECTION PROTOCOL

1) Image acquisition

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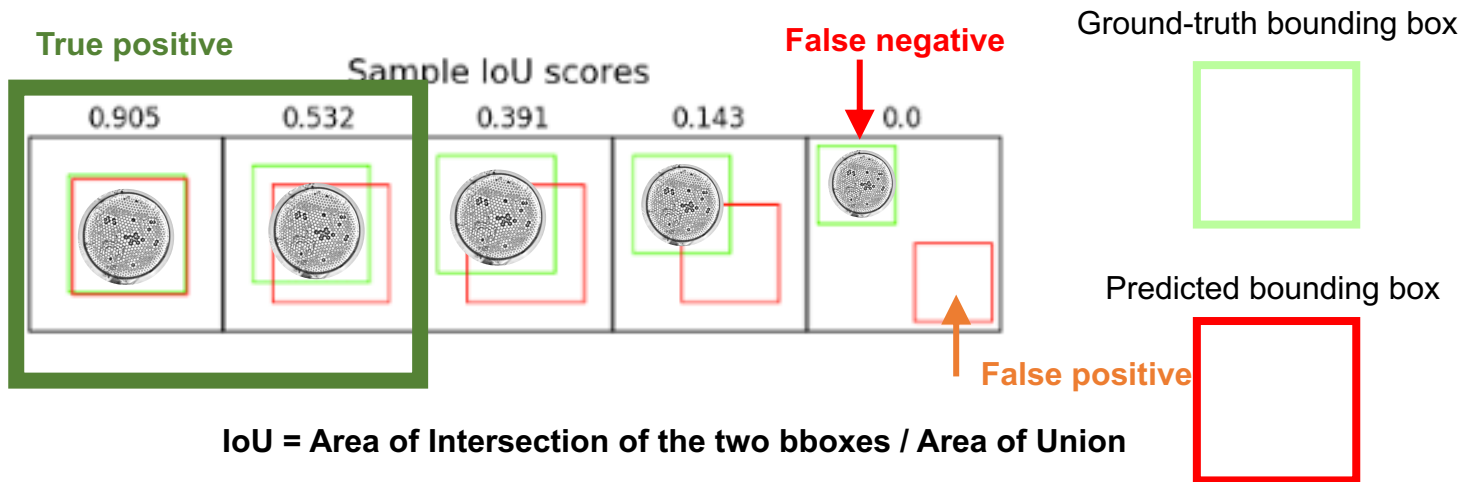
3) Object classification

- Image library construction
- Model training
- Inference on new images

1) Image annotation using CVAT (Computer Vision Annotation Tool)

2) **Model training:**

How to evaluate model performance ?



To measure model performance, you can measure :

Mean Average Precision = $\frac{\text{True Positive}}{\text{True Positive} + \text{False Positive}}$: is the model precise? Does it generate many false positives?

Mean Average Recall = $\frac{\text{True Positive}}{\text{True Positive} + \text{False Negative}}$: did the model find all the ground-truth boxes?

OBJECT DETECTION PROTOCOL

1) Image acquisition

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3) Object classification

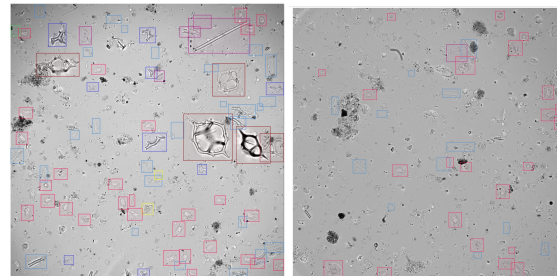
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1) Image annotation using CVAT (Computer Vision Annotation Tool)

2) **Model training:**

How to evaluate model performance ?

Precision



IoU metric: bbox

Average Precision (AP) @[IoU=0.50:0.95 area= all maxDets=100]	= -1.000
Average Precision (AP) @[IoU=0.50 area= all maxDets=300]	= 0.751
Average Precision (AP) @[IoU=0.75 area= all maxDets=300]	= 0.567
Average Precision (AP) @[IoU=0.50:0.95 area= small maxDets=300]	= -1.000
Average Precision (AP) @[IoU=0.50:0.95 area=medium maxDets=300]	= 0.389
Average Precision (AP) @[IoU=0.50:0.95 area= large maxDets=300]	= 0.587

75% of the boxes that the model predicts actually correspond to ground-truth boxes

OBJECT DETECTION PROTOCOL

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1) Image annotation using CVAT (Computer Vision Annotation Tool)

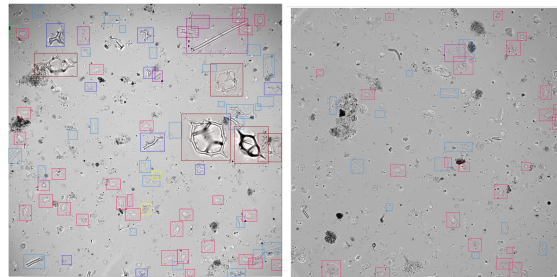
2) **Model training:**

How to evaluate model performance ?

Recall

IoU metric: bbox

Average Recall	(AR) @[IoU=0.50:0.95 area= all maxDets= 10]	= 0.181
Average Recall	(AR) @[IoU=0.50:0.95 area= all maxDets= 30]	= 0.405
Average Recall	(AR) @[IoU=0.50:0.95 area= all maxDets=300]	= 0.578
Average Recall	(AR) @[IoU=0.50:0.95 area= small maxDets=300]	= -1.000
Average Recall	(AR) @[IoU=0.50:0.95 area=medium maxDets=300]	= 0.505
Average Recall	(AR) @[IoU=0.50:0.95 area= large maxDets=300]	= 0.657

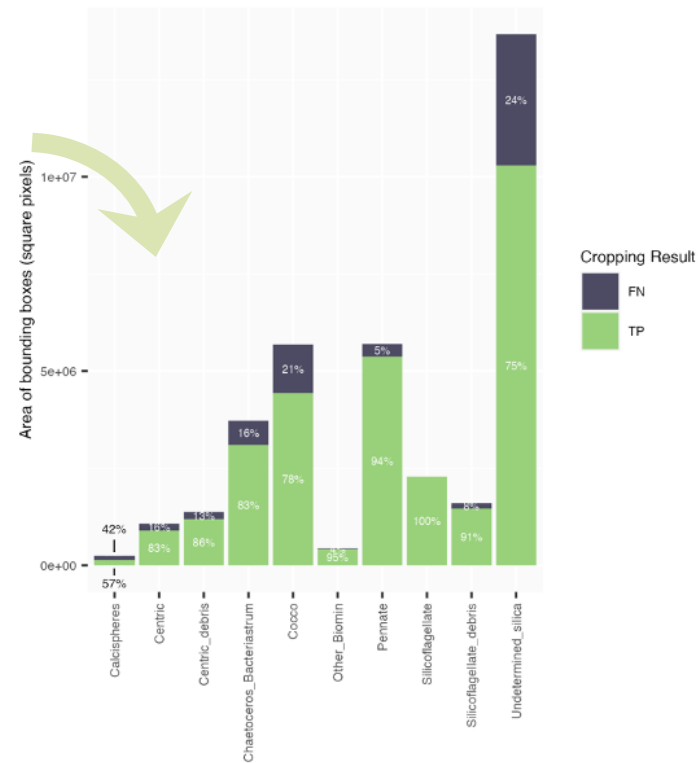
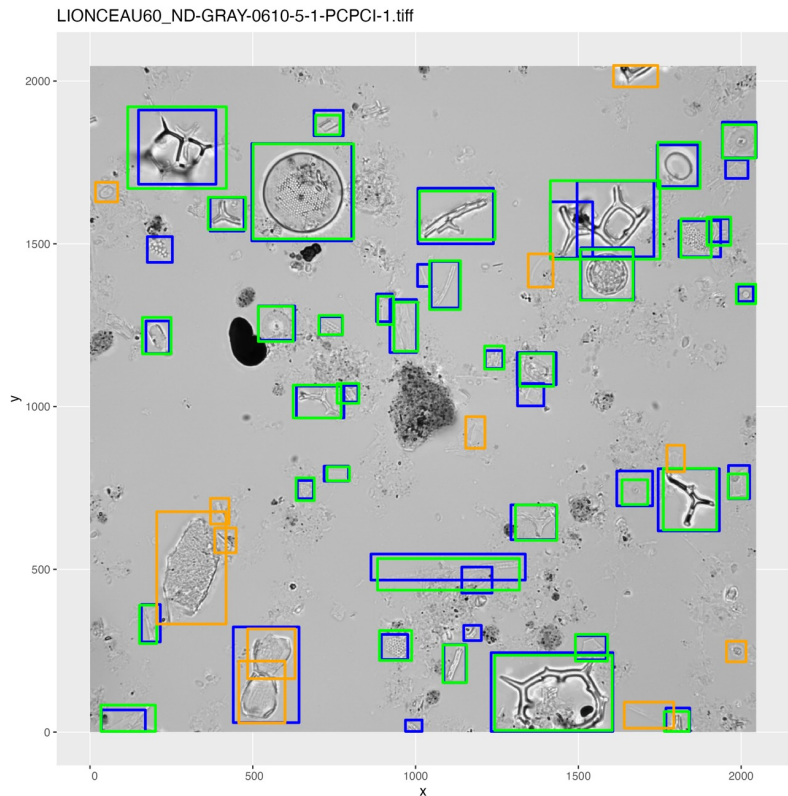
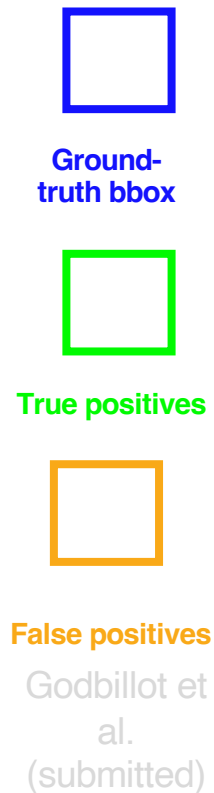


Over a range of IoUs, 58% of the ground-truth bounding boxes were found by the model

- the number increases if you only consider the large objects
- the value for recall is averaged over a range of different IoU thresholds

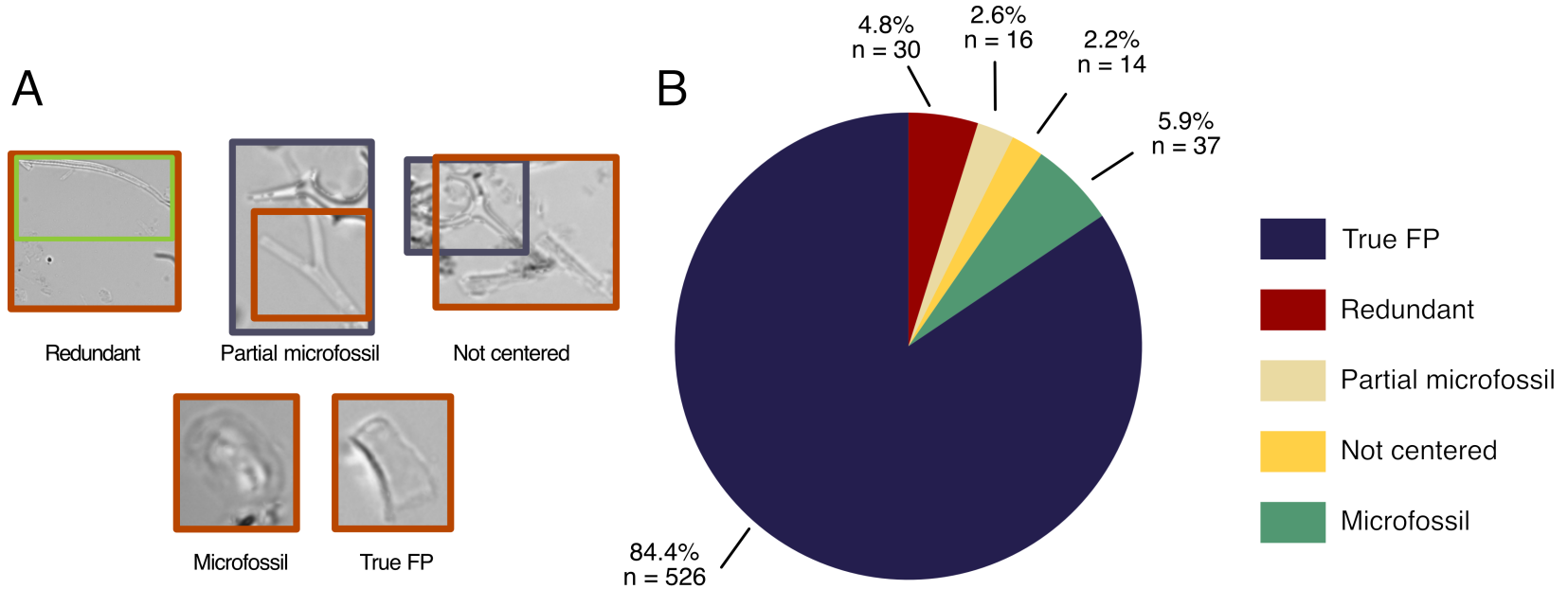
OBJECT DETECTION PROTOCOL

How does this translate on a test image set? → RECALL:



OBJECT DETECTION PROTOCOL

How does this translate on a test image set? → PRECISION:



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ADVANTAGES

- **Perform inference and crop 200 images in 30s** → very efficient
- **Does not miss rare species**

→ **Now possible to study automatically** the production of different phytoplankton groups in the same sample

DRAWBACKS

- **Classification step is independent of detection step** (because of rare species)
 - → doubles the efforts to build an image library and train models
- **No real-time cropping possible**
 - → requires memory to store the images
 - → can only work on the “hyperfocused” image → loss of information → cannot go down to species level.
- **Capacity for generalization to other types of plankton images (filters etc.) is limited**

Short-term:

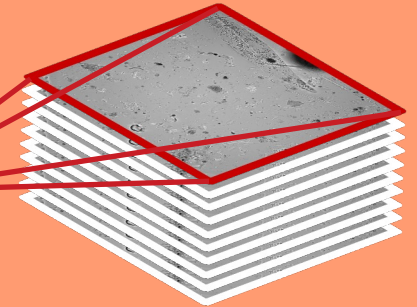
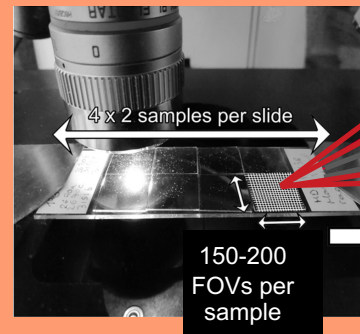
Compare Faster R-CNN and YOLO results

Medium-term:

Explore ways to build “artificial slides” to increase rare species → build new library to perform **detection + classification in a single step**

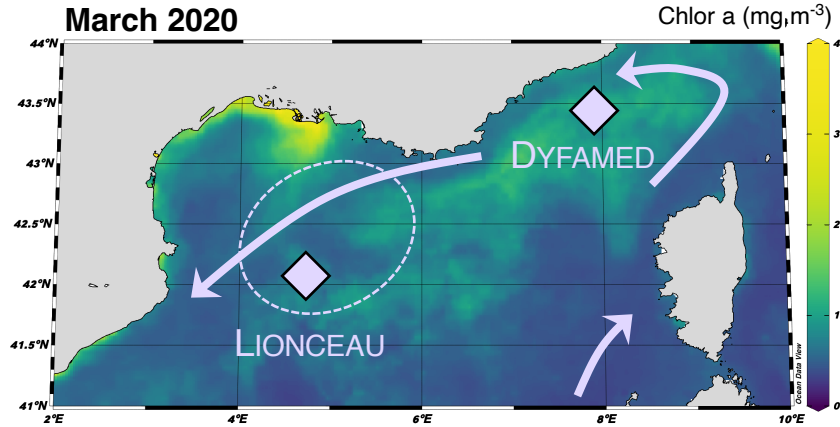
Long-term:

Work on the image stack in real time → use entire stack to extract more information → species (but loss of images if ever models are improved after acquisition)



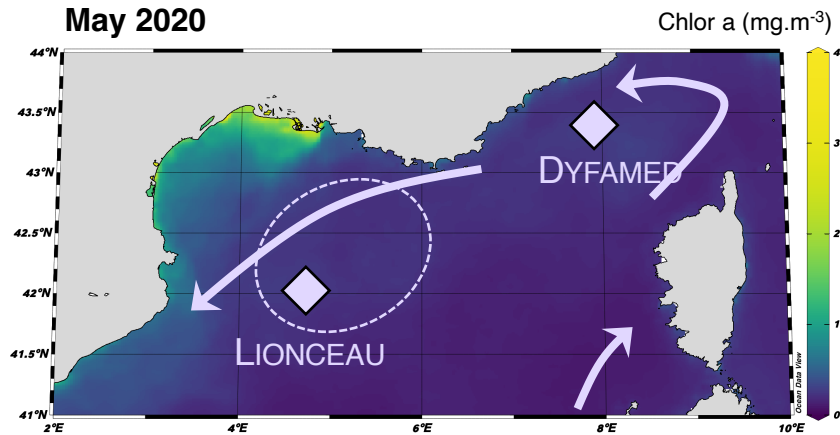
Example results from the Mediterranean Sea

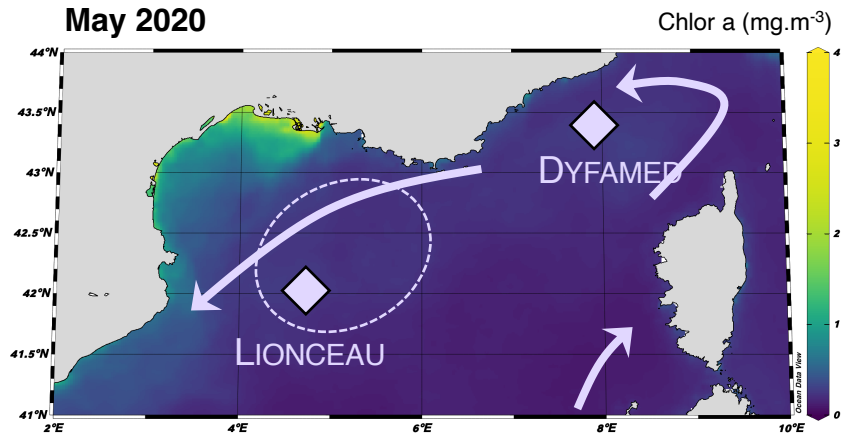
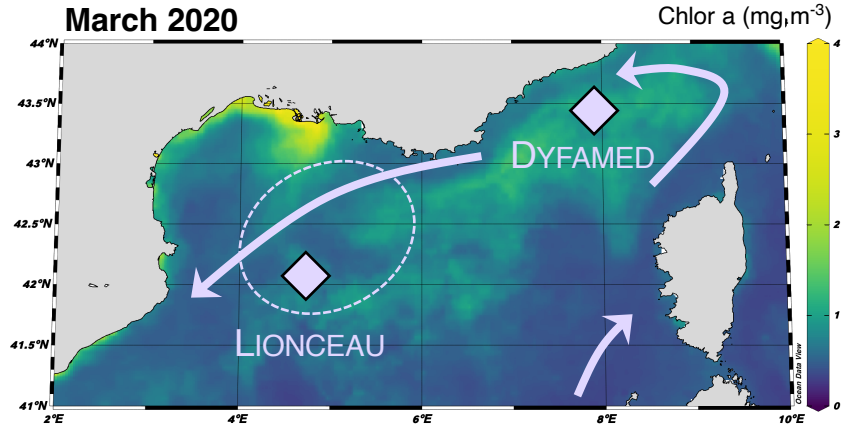
APPLICATIONS



Two sediment trap series from the NW Mediterranean (2010-2020); approx. 2 weeks per point

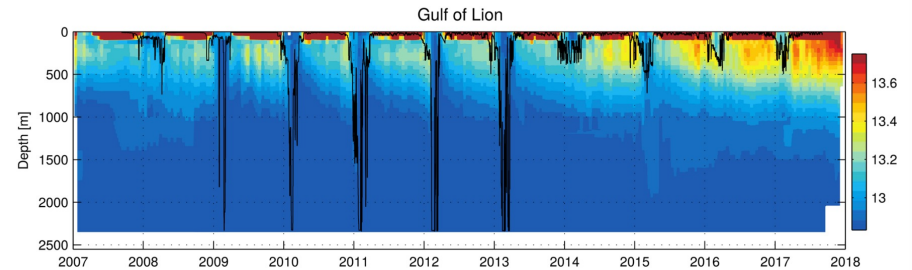
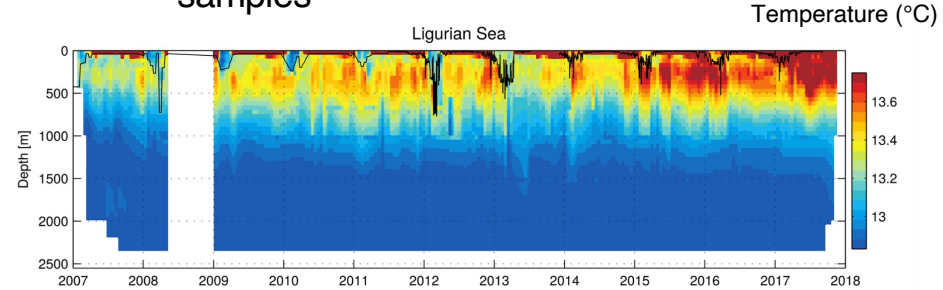
- Dyfamed (Ligurian Sea; 1000m depth), 246 samples
- Lionceau (Gulf of Lion; 2400m depth), 80 samples

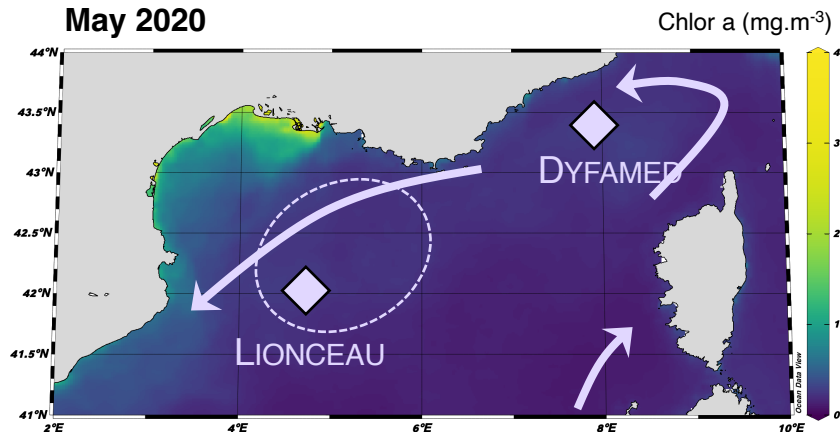
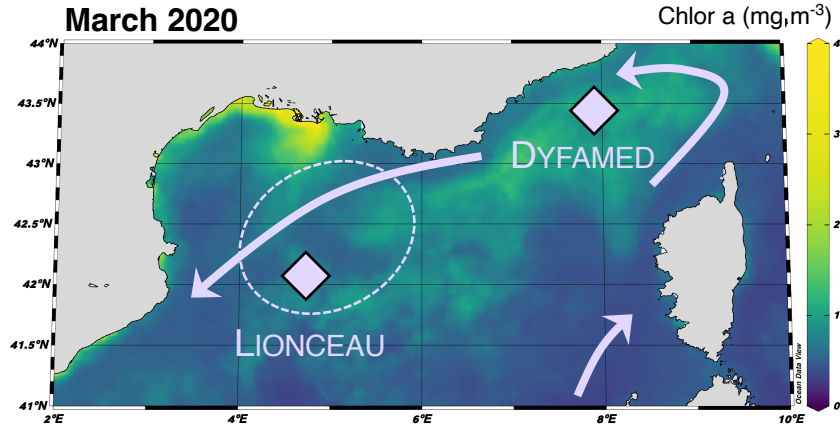




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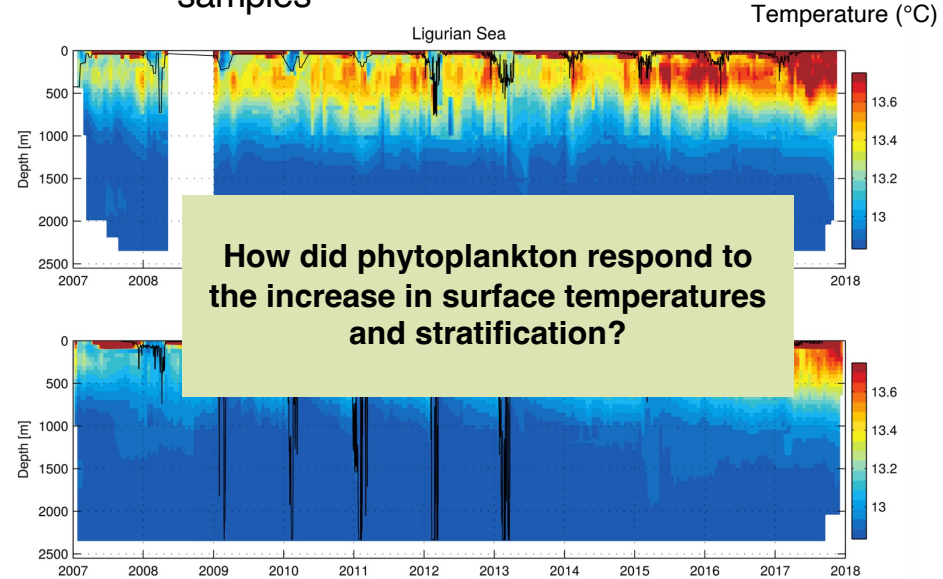
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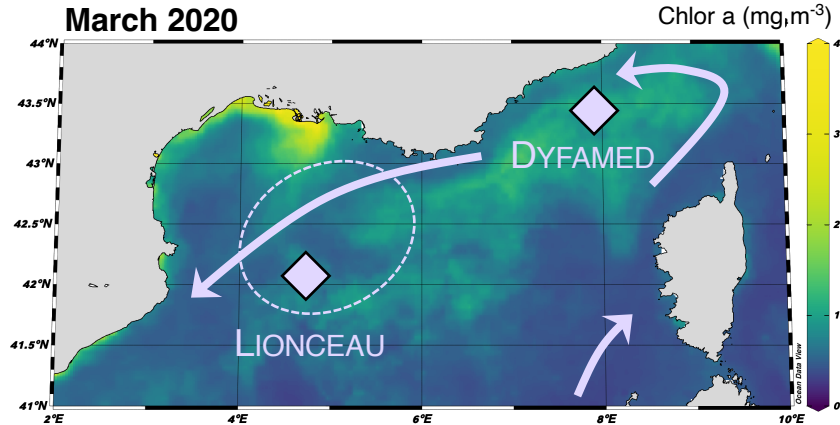


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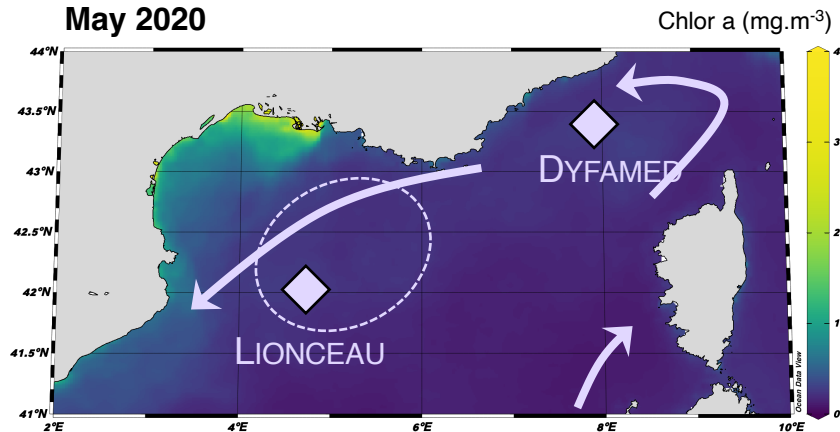


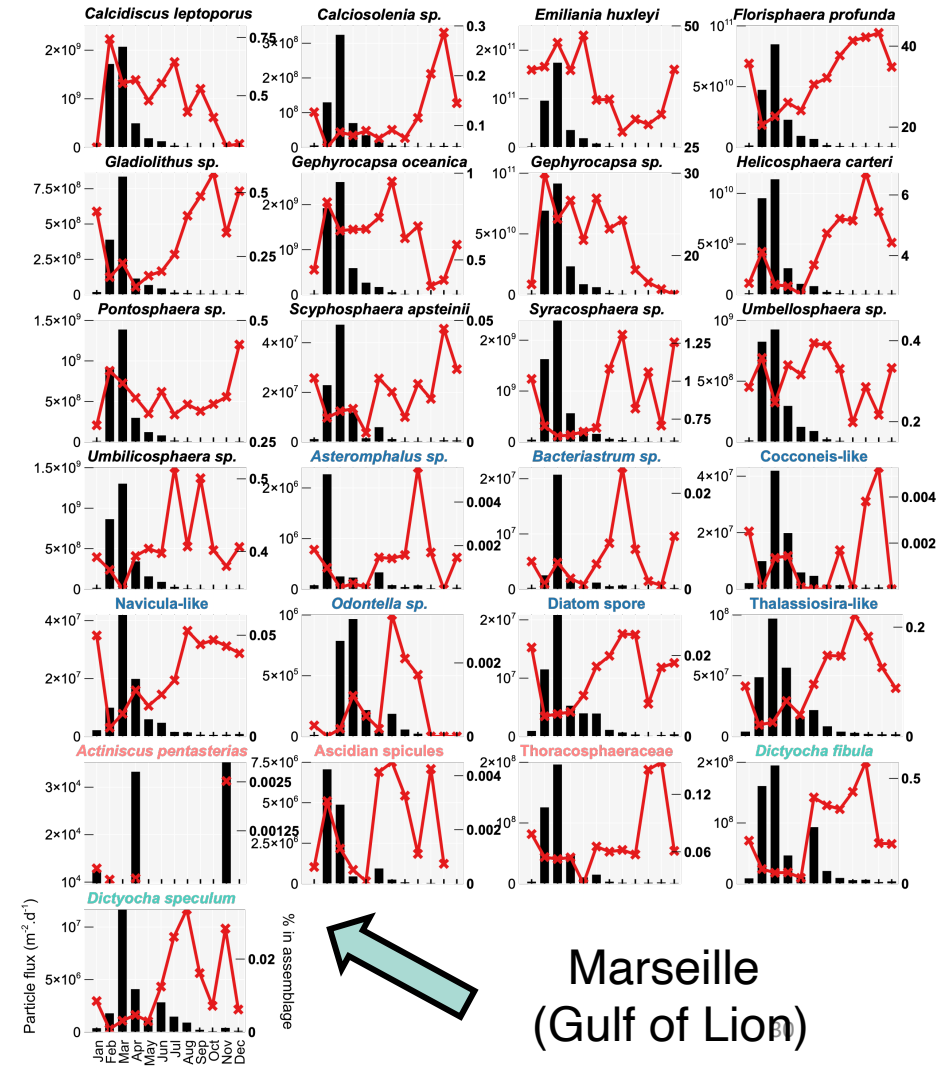
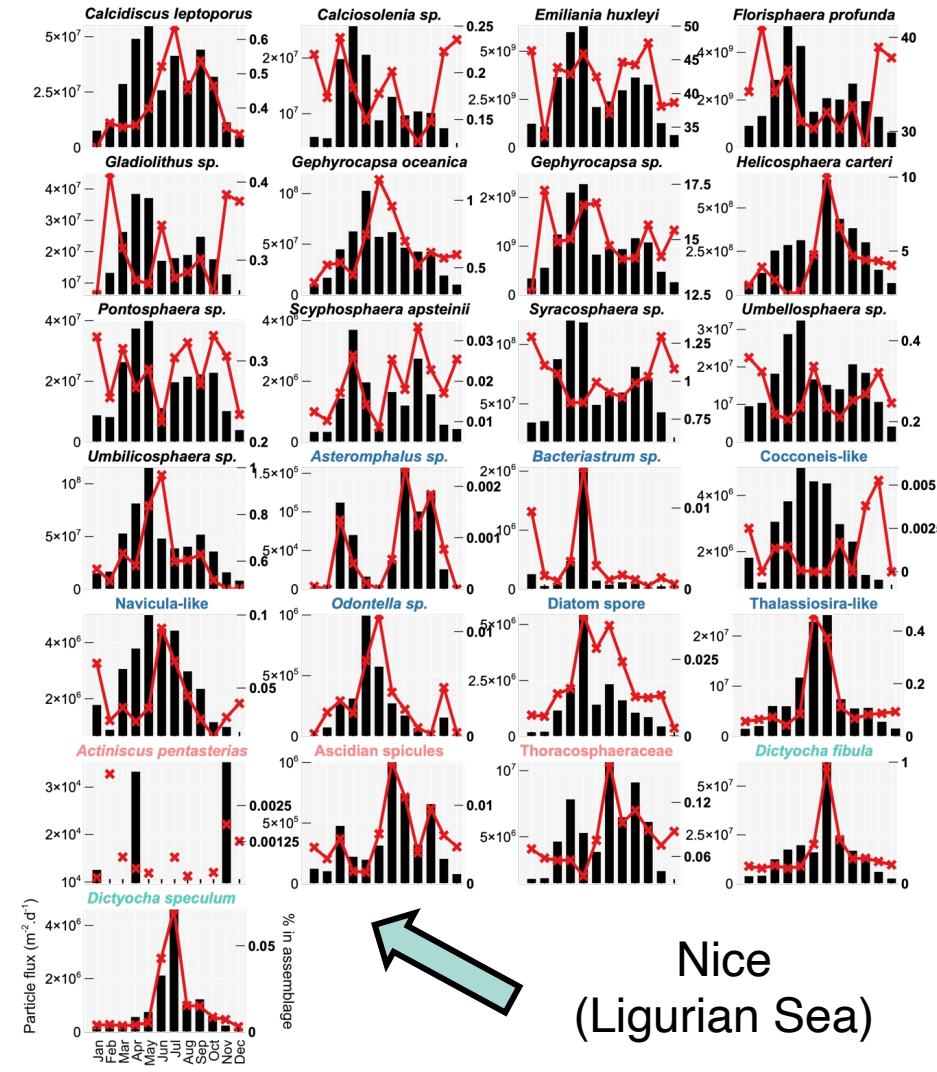
APPLICATIONS

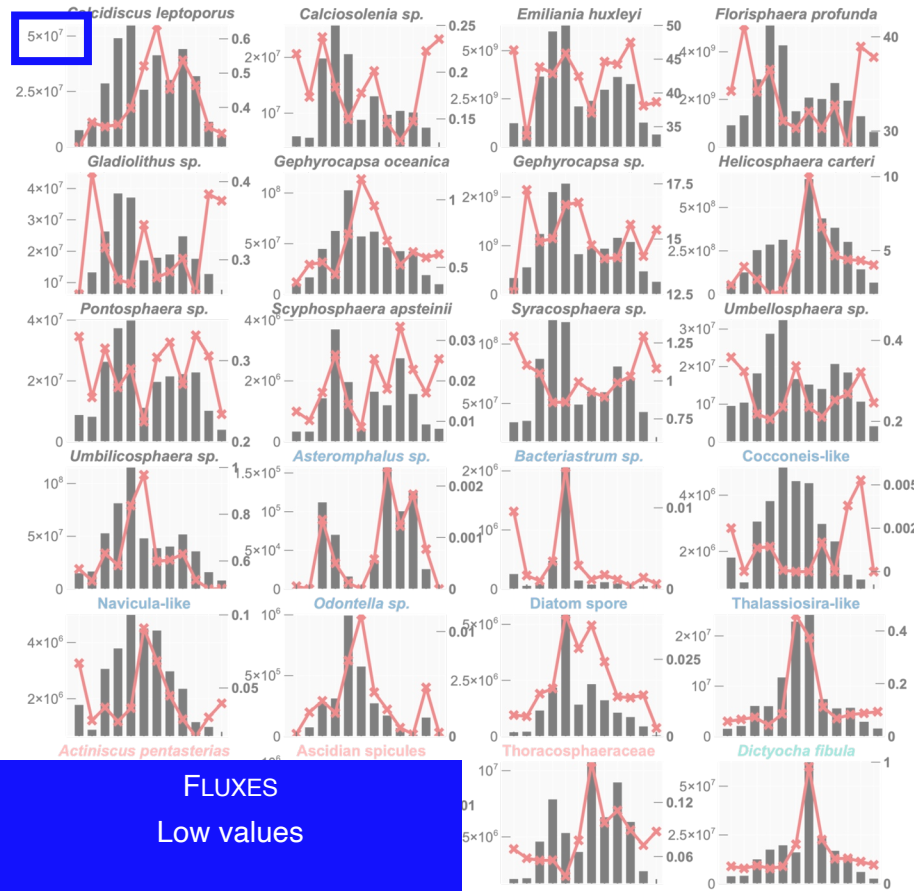


For the purpose of this study

- > 90 000 images
- A couple million particles sorted
- Several thousand plankton remains counted

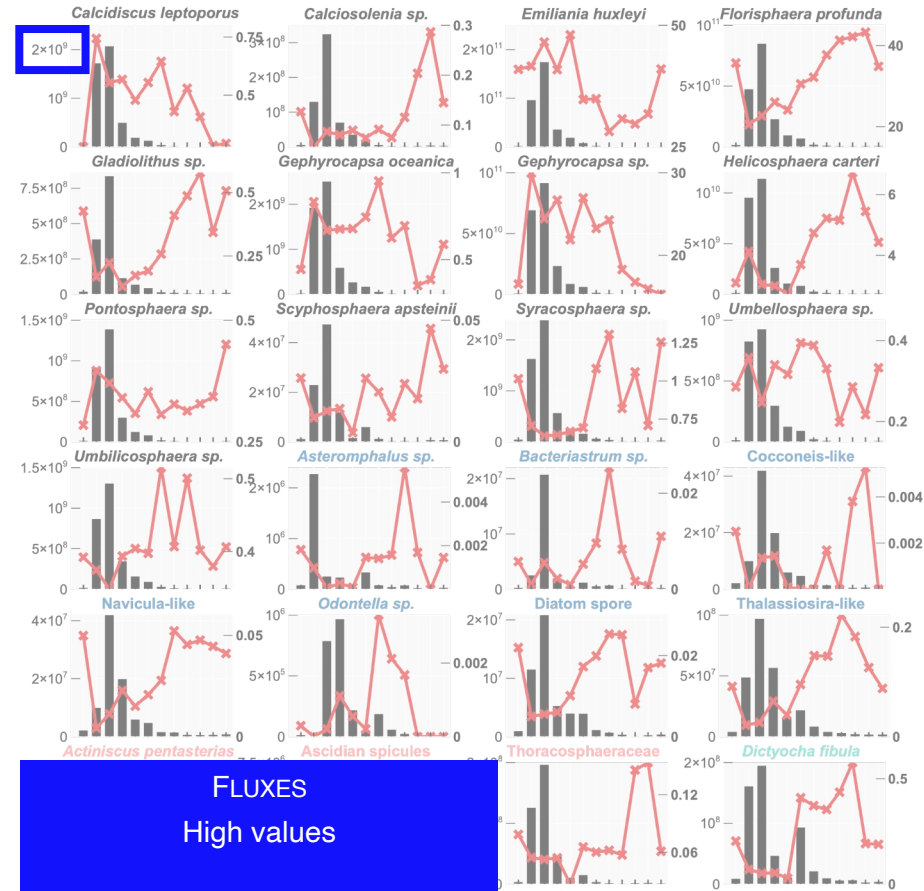






FLUXES
Low values

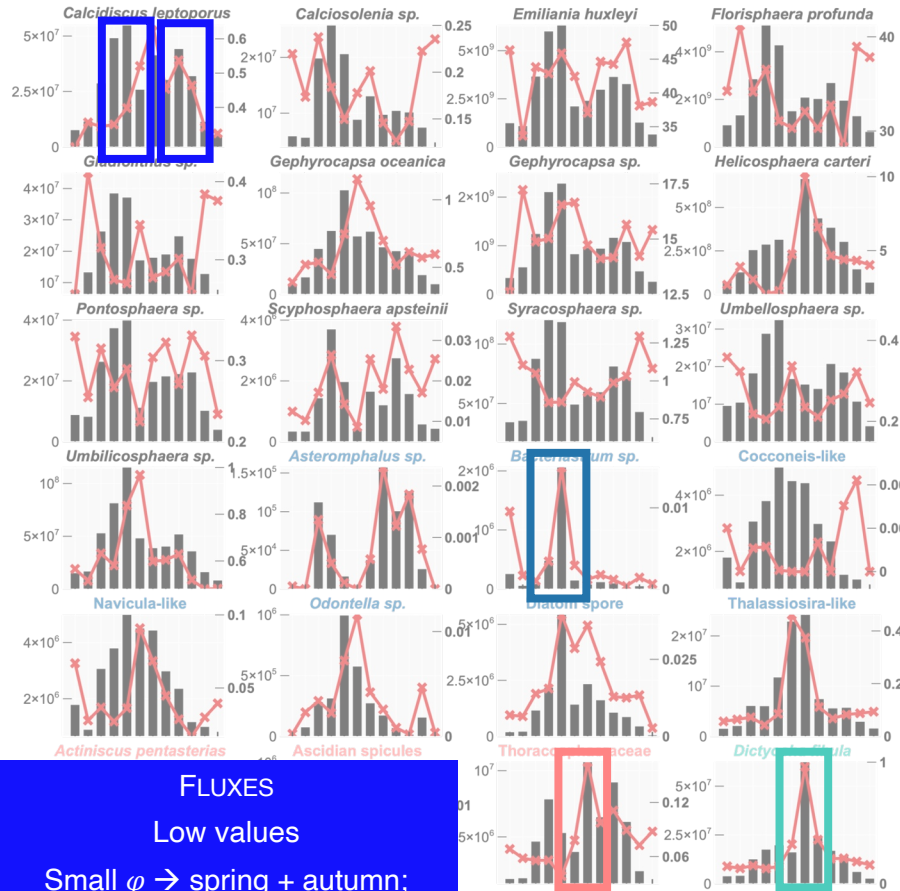
Nice
(Ligurian Sea)



FLUXES
High values

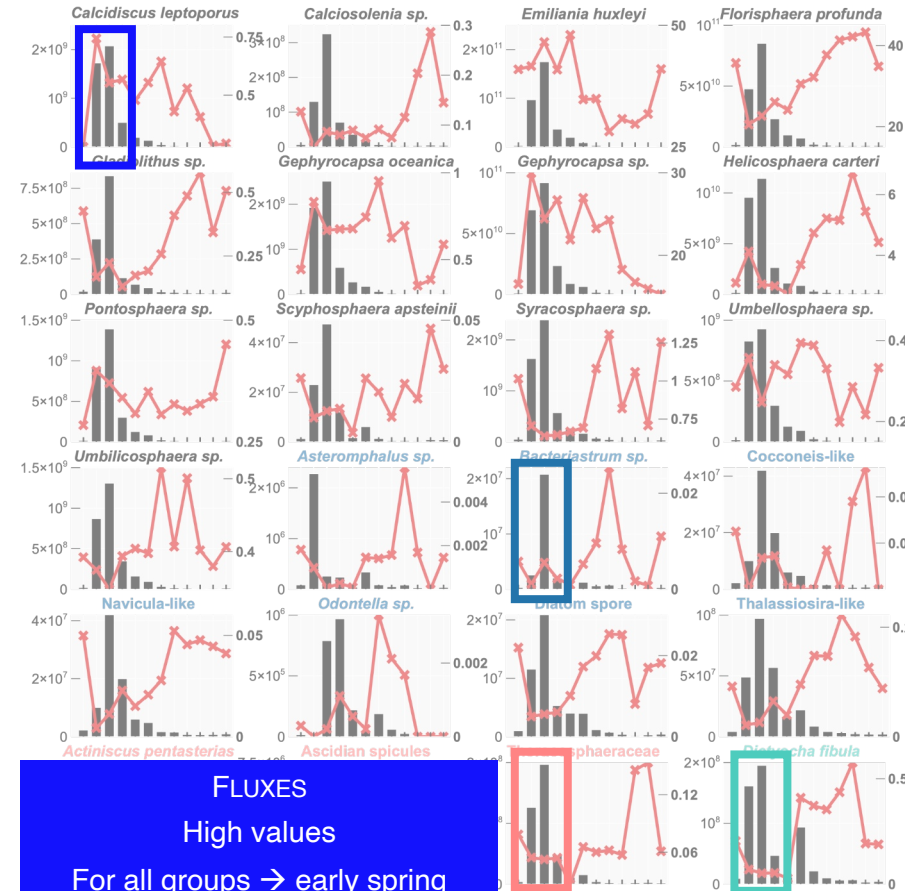
Marseille
(Gulf of Lion)

Particle flux (m³ d⁻¹)



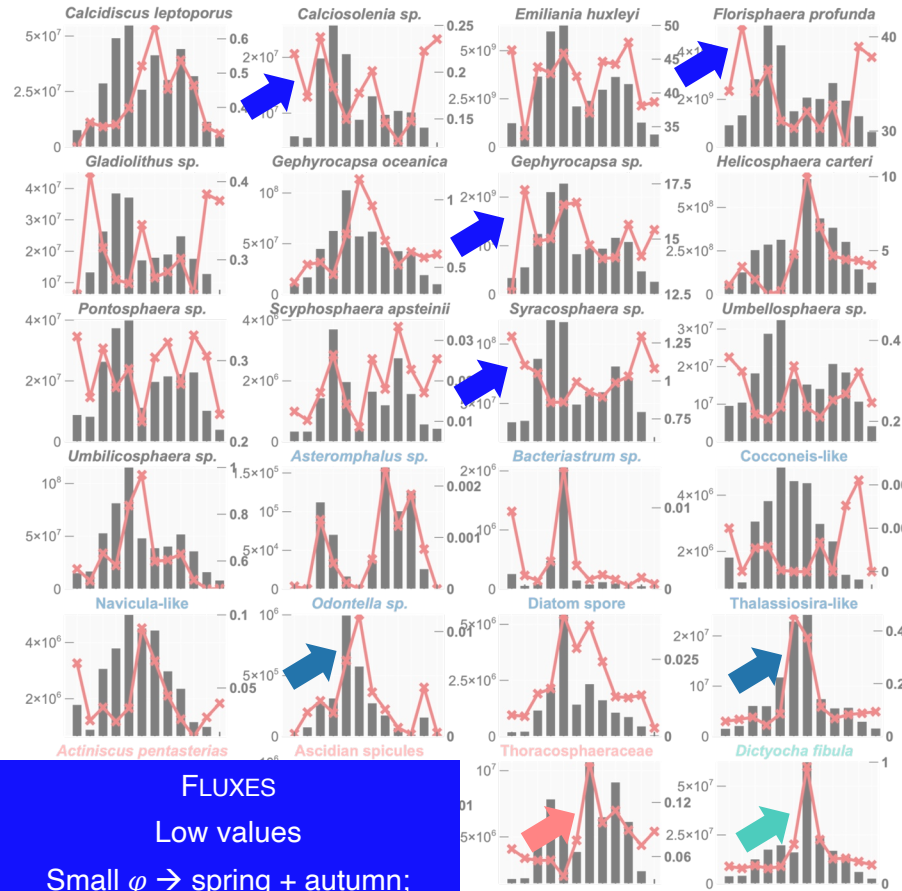
FLUXES
 Low values
 Small $\varphi \rightarrow$ spring + autumn;
 large(r) $\varphi \rightarrow$ summer

Nice
 (Ligurian Sea)



FLUXES
 High values
 For all groups \rightarrow early spring
PERCENTAGES
 Marseille
 (Gulf of Lion)

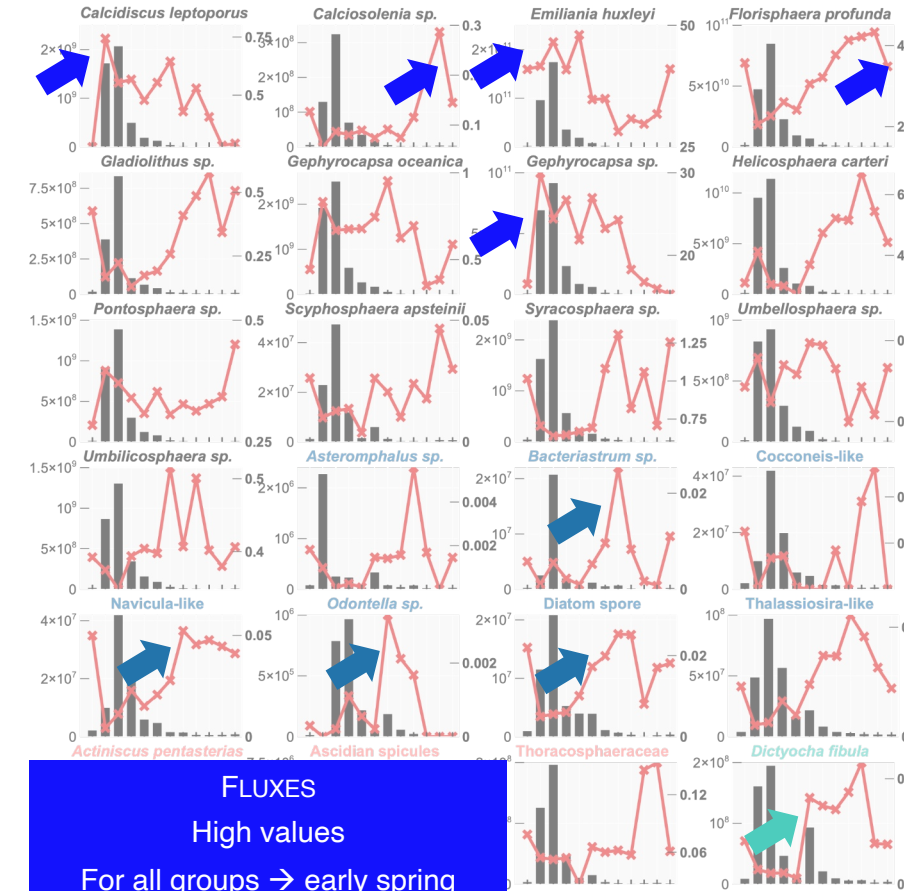
Particle flux (m³ of 1)



FLUXES
 Low values
 Small $\varphi \rightarrow$ spring + autumn;
 large(r) $\varphi \rightarrow$ summer

PERCENTAGES
 Small $\varphi \rightarrow$ winter + spring;
 large(r) $\varphi \rightarrow$ summer + autumn

Nice
 (Ligurian Sea)



FLUXES
 High values
 For all groups \rightarrow early spring

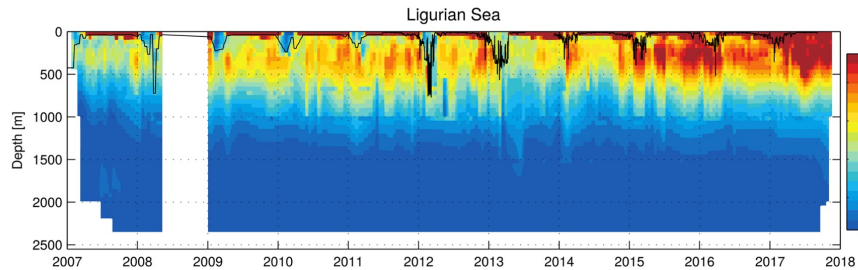
PERCENTAGES
 Small $\varphi \rightarrow$ winter + spring;
 large(r) $\varphi \rightarrow$ summer + autumn

Marseille
 (Gulf of Lion)

Particle flux (m⁻² d⁻¹)

FLUXES
Low values

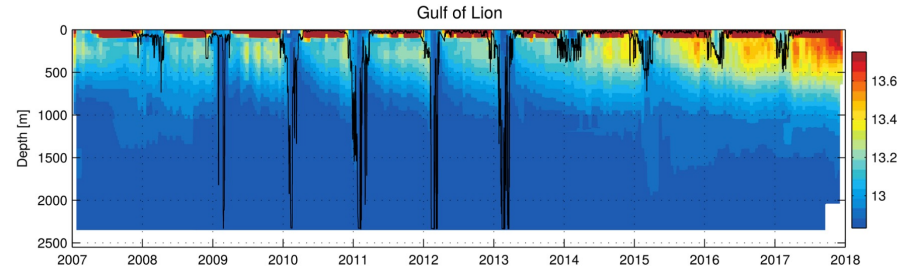
Nice
(Ligurian Sea)



Margirier et al. 2020

FLUXES
High values

Marseille
(Gulf of Lion)



Margirier et al. 2020

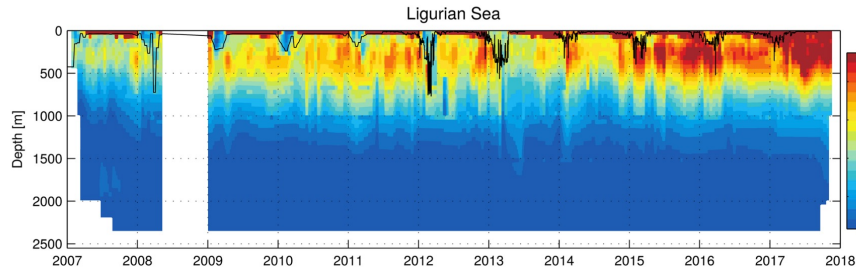
Episodes of **deep convection** are important for the transport of material to the sea floor, and, by extension, for carbon storage at depth

FLUXES

Low values

Small $\varphi \rightarrow$ spring + autumn;
large(r) $\varphi \rightarrow$ summer

Nice (Ligurian Sea)



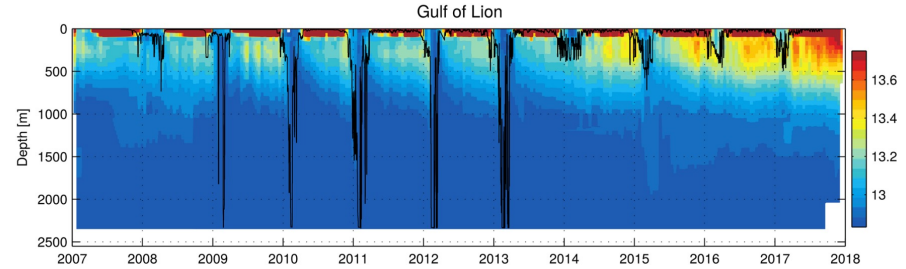
Margirier et al. 2020

FLUXES

High values

For all groups \rightarrow early spring

Marseille (Gulf of Lion)



Margirier et al. 2020

Episodes of **deep convection** are important for the transport of material to the sea floor, and, by extension, for carbon storage at depth

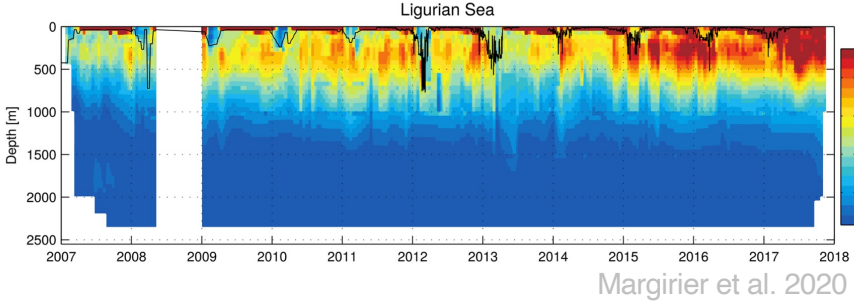
In the Gulf of Lion, phytoplankton fluxes reflect deep water convection episodes. In the Ligurian Sea, they could also reflect, in part, the biological activity in the surface ocean

APPLICATIONS

FLUXES
 Low values
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 large(r) $\varphi \rightarrow$ summer

PERCENTAGES
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Nice (Ligurian Sea)



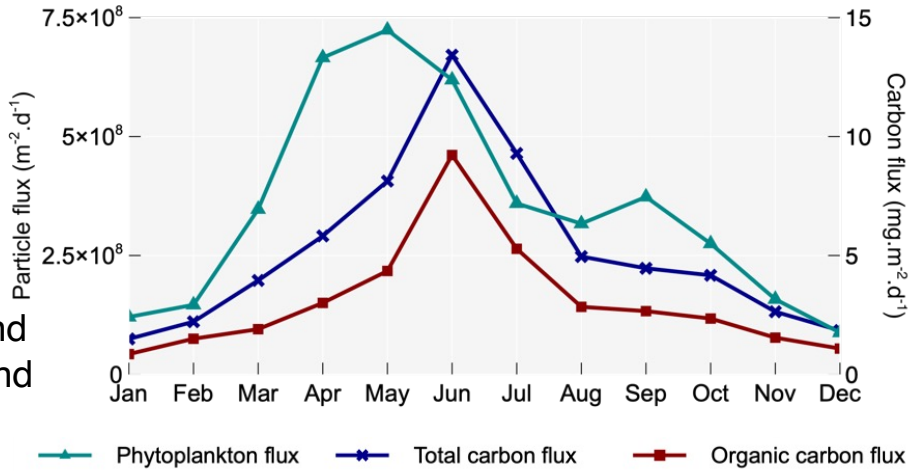
Overall, while small phytoplankton dominate in winter and spring, larger phytoplankton dominates in the summer and fall:

\rightarrow Can this explain why carbon burial in the Ligurian Sea is highest in the summer?

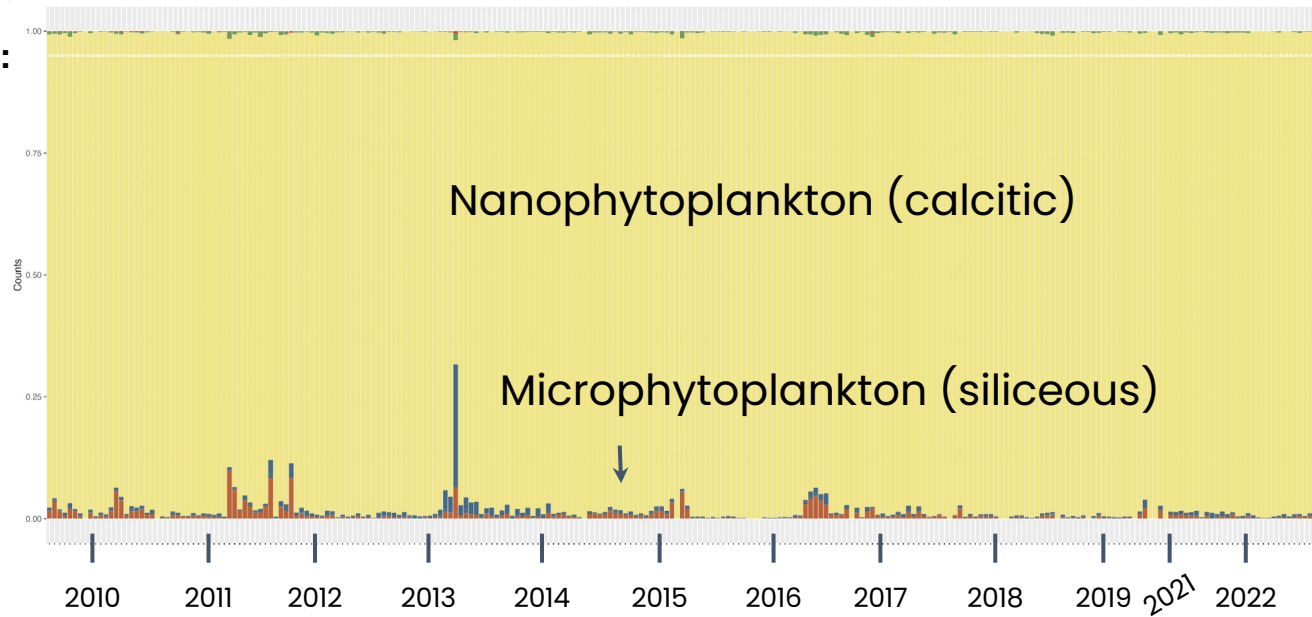
FLUXES
 High values
 For all groups \rightarrow early spring

PERCENTAGES
 Small $\varphi \rightarrow$ winter + spring;
 large(r) $\varphi \rightarrow$ summer + autumn

Marseille (Gulf of Lion)



Ligurian Sea example:



What is the impact of environmental change over the last decade;
If microphytoplankton decreases in the assemblage, will this impact carbon storage in the
Mediterranean?

Use of AI in plankton studies:

Pros:

- Once trained, detection and classification workflows can **process data much more efficiently** than an expert
- Are a useful means of obtaining **standardized time-series** (*i.e.* results will not depend on who the observer was)
- Make it possible for **untrained researchers** to obtain high resolution time-series → increase number of observations

Cons:

- Training libraries are tedious to obtain
- Problems with precision when it comes to rare species
- Capacity for generalization to other types of plankton images is limited → image libraries are instrument-specific